

Non-Euclidean Representations

Embedding
 Pseudo Euclidean Space
 Classifiers in PE Space
 Euclidean Corrections
 Causes
 Informativeness

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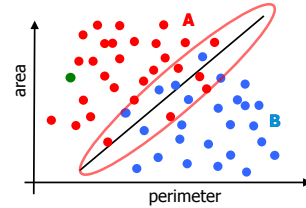
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Feature Representation

Objects \rightarrow points in a Euclidean Space
 Features reduce \rightarrow classes overlap
 \rightarrow to be solved by statistics



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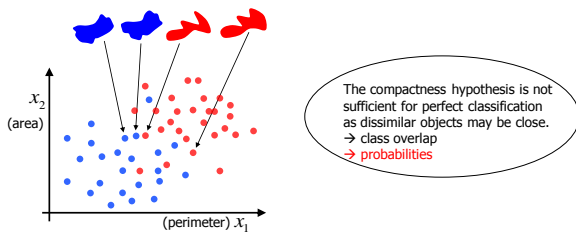
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Compactness

Representations of real world similar objects are close.
 There is no ground for any generalization (induction) on representations that do not obey this demand.



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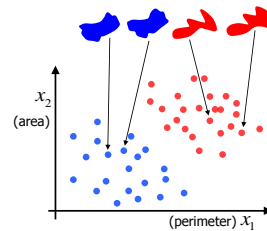
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A.G. Arkedev and E.M. Braverman, *Computers and Pattern Recognition*, 1966.



True Representations



Similar objects are close
and
 Dissimilar objects are distant.

\rightarrow no probabilities needed, domains are sufficient!

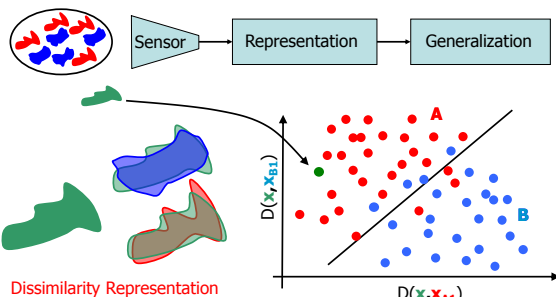
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Dissimilarities \rightarrow True Representation



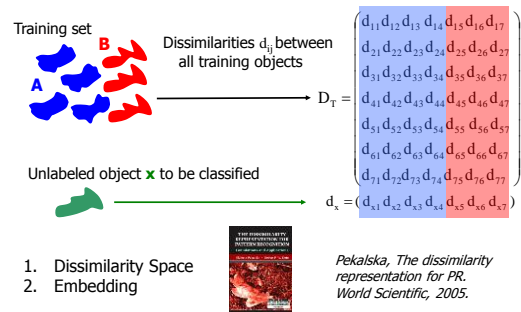
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Alternatives for the Nearest Neighbor Rule



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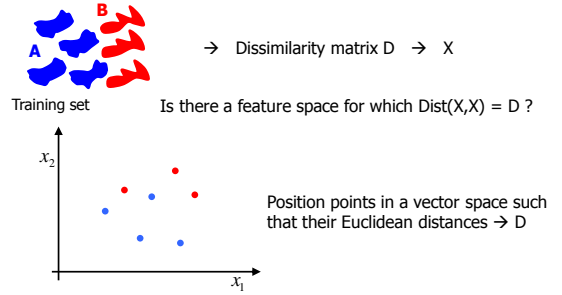
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Embedding of (non-Euclidean) Dissimilarities

Alternative 2: Embedding



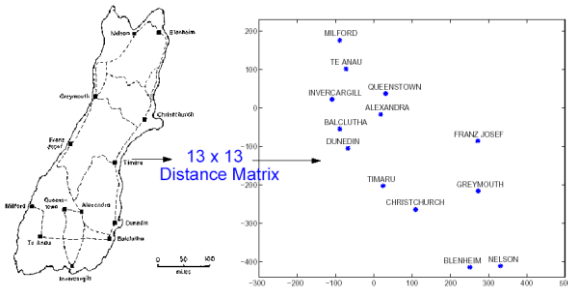
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Embedding



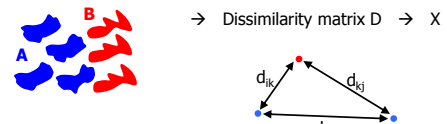
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Embedding of non-metric measurements



If the dissimilarity matrix **cannot be explained from a vector space**, (e.g. for Hausdorff and Hamming distance of images) or if $d_{ij} > d_{ik} + d_{kj}$ (**triangle inequality not satisfied**) embedding in Euclidean space not possible \rightarrow Pseudo-Euclidean embedding

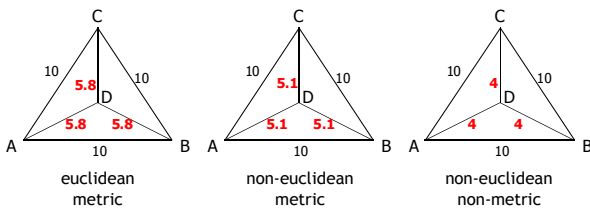
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Euclidean - Non Euclidean - Non Metric



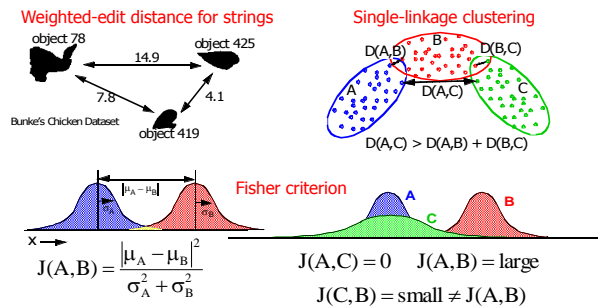
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Non-metric distances



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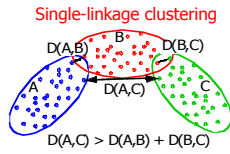
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Intrinsically Non-Euclidean Dissimilarity Measures Single Linkage



Distance(Table,Book) = 0
Distance(Table,Cup) = 0
Distance(Book,Cup) = 1



Pseudo-Euclidean Space

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(Pseudo-)Euclidean Embedding

$m \times m$ D is a given, imperfect dissimilarity matrix of training objects.

Construct inner-product matrix: $B = -\frac{1}{2}JD^{(2)}J$ $J = I - \frac{1}{m}\mathbf{1}\mathbf{1}^T$

Eigenvalue Decomposition, $B = Q\Lambda Q^T$

Select k eigenvectors: $X = Q_k \Lambda_k^{-\frac{1}{2}}$ (problem: $\Lambda_k < 0$)

Let \mathfrak{S}_k be a $k \times k$ diag. matrix, $\mathfrak{S}_k(i,i) = \text{sign}(\Lambda_k(i,i))$

$\Lambda_k(i,i) < 0 \rightarrow$ Pseudo-Euclidean

$n \times m$ D_z is the dissimilarity matrix between new objects and the training set.

The inner-product matrix: $B_z = -\frac{1}{2}(D_z^{(2)}J - \frac{1}{n}\mathbf{1}\mathbf{1}^T D^{(2)}J)$

The embedded objects: $Z = B_z Q_k |\Lambda_k|^{-\frac{1}{2}} \mathfrak{S}_k$

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(Pseudo-)Euclidean Embedding

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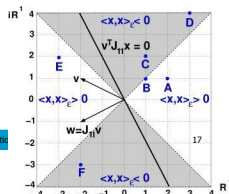
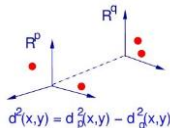
PES: Pseudo-Euclidean Space (Krein Space)

If D is non-Euclidean, B has p positive and q negative eigenvalues.

A pseudo-Euclidean space \mathcal{E} with signature (p,q) , $k = p+q$, is a non-degenerate inner product space $\mathfrak{R}_k = \mathfrak{R}_p \oplus \mathfrak{R}_q$ such that:

$$\langle x, y \rangle_{\mathcal{E}} = x^T \mathfrak{S}_{pq} y = \sum_{i=1}^p x_i y_i - \sum_{j=p+1}^q x_j y_j \quad \mathfrak{S}_{pq} = \begin{bmatrix} I_{p \times p} & 0 \\ 0 & -I_{q \times q} \end{bmatrix}$$

$$d_{\mathcal{E}}^2(x, y) = \langle x - y, x - y \rangle_{\mathcal{E}} = d_p^2(x, y) - d_q^2(x, y)$$

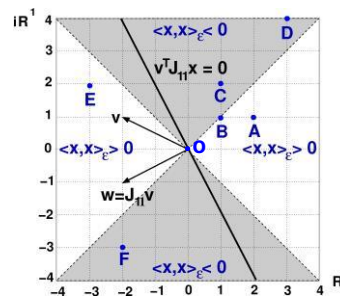


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Distances in PES



$$d^2(O, A) > 0$$

$$d^2(O, E) > 0$$

$$d^2(O, B) = 0$$

$$d^2(O, D) < 0$$

All points in the grey area are closer to O than O itself !?

Any point has a negative square distance to some points on the line $v^T J_11 x = 0$.

Can it be used as a classifier?

Can we define a margin as in the SVM?

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Pseudo Euclidean Space

Euclidean embedding $D \rightarrow X$

$$d_{ij}^2 = \|\mathbf{x}_i - \mathbf{x}_j\|^2$$

Pseudo Euclidean embedding $D \rightarrow \{X^p, X^q\}$

$$d_{ij}^2 = \|\mathbf{x}_i^p - \mathbf{x}_j^p\|^2 - \|\mathbf{x}_i^q - \mathbf{x}_j^q\|^2$$

'Positive' and 'negative' space,
Compare Minkowsky space in relativity theory

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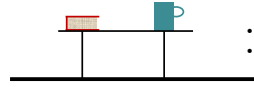
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Embedding Example

	Table	Book	Cup
Table	0	0	0
Book	0	0	1
Cup	0	1	0
Floor	0	1	1



- Embed table, book, cup in a 2D PE space
- Project the floor

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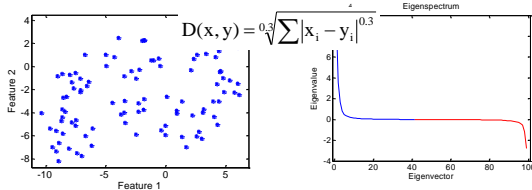
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Pseudo-Euclidean Embedding

If D is non-Euclidean then B has p positive and q negative eigenvalues



Solutions:

- Remove all eigenvectors with small and negative eigenvalues
- or, take absolute values of eigenvalues and proceed
- or, construct a pseudo-Euclidean space

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Negative Euclidean Fraction

$$NEF = \frac{\sum_{\lambda_i < 0} |\lambda_i|}{\sum_{\forall \lambda_i} |\lambda_i|}$$

$$0 \leq NEF \leq 1$$

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PE Space \leftrightarrow Kernels

$$K(x, y) = -\frac{1}{2} J D(x, y)^{(2)} J \quad J = I - \frac{1}{m} \mathbf{1}\mathbf{1}^T$$

may be considered as a kernel. If

$$K(x, y) = \langle L(x), L(y) \rangle$$

- The **kernel trick** may be used: operations defined on inner products in kernel space can be operated directly on $K(x, y)$ **without embedding!**
- True for **Mercer kernels** (all eigenvalues ≥ 0).
- Difficult for **indefinite kernels**.
- Studying classifiers in **PE space** is studying the indefinite **kernel space**.
- Dissimilarities are more informative than kernels (due to normalization).

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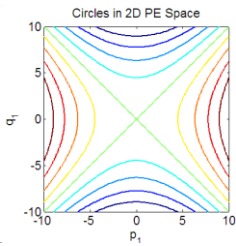
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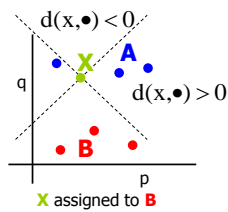


Classifiers in Pseudo-Euclidean Space

Distance based classifiers in PE Space



Metric in PE Space.
Equidistant points to the origin.



Nearest Neighbour and Nearest Mean can be properly defined.
SVM ? What is the distance to a line?

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PE-Space classifiers

- kNN, Parzen, Nearest Mean
As object distances can be computed (are known)
- LDA, QDA
As PE inner possibly product definitions cancel they can be computed, interpretation ... ?
- SVM
May get a result (indefinite kernel), possibly not optimal
- Others ??

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SVM in PE Space

- SVM on indefinite kernels may not converge as Mercer's conditions are not fulfilled.
- However, if it converges the solution is proper:
 $|w^T \zeta w|$
is minimized.
- See also: B. Haasdonk, *Feature Space Interpretation of SVMs with Indefinite Kernels*, IEEE PAMI, 24, 482-492, 2005.

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Densities in PE Space

- Densities can be defined in a vector space on de basis of volumes, without the need of a metric.
- Density estimates however, often need a metric.
E.g. the Parzen estimator:
$$\hat{f}(x) = \frac{1}{n} \sum_{y_i} c \exp\left(-\frac{d(x, y_i)^2}{2h^2}\right)$$

needs a distance definition $d(x, y)$.
- There is no problem, however, in case for all objects $d(x, y) > 0$.
- How can Gaussian densities be defined?
- Note that QDA in PES is identical to the QDA in AES as the signature cancels. The relation with a Gaussian distribution, however, is lost.

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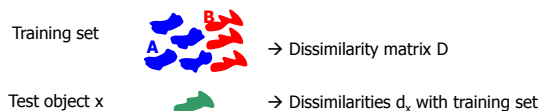
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Dissimilarity based classifiers compared

Dissimilarity based classification procedure compared



1. Nearest Neighbour Rule
 2. Reduce training set to representation set
⇒ dissimilarity space
 3. Embedding: Select large $\Lambda_{ii} > 0 \Rightarrow$ Euclidean space
Select large $|\Lambda_{ij}| > 0 \rightarrow$ pseudo-Euclidean space
- } discriminant function

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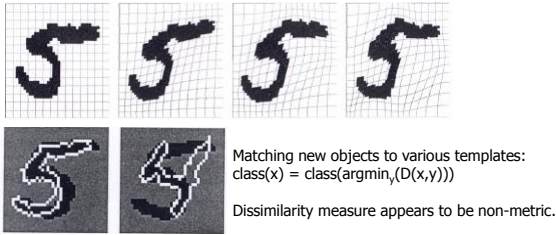
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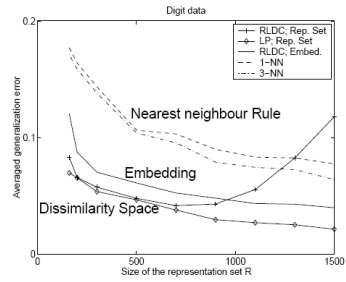
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Examples Dissimilarity Measures



Three Approaches Compared for the Zongker Data



Dissimilarity Space equivalent to Embedding better than Nearest Neighbour Rule

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A.K. Jain, D. Zongker, Representation and recognition of handwritten digit using deformable templates, IEEE-PAMI, vol. 19, no. 12, 1997, 1386-1391.



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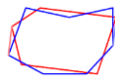
Polygon Data



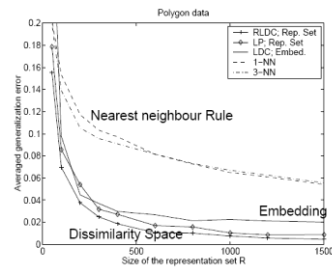
Minimum edge length: 0.1 of maximum edge length

Distance measures: Hausdorff $D = \max \{ \max_i(\min_j(d_{ij})), \max_j(\min_i(d_{ij})) \}$.
 Modified Hausdorff $D = \max \{ \text{mean}_i(\min_j(d_{ij})), \text{mean}_j(\min_i(d_{ij})) \}$. (no metric!)
 d_{ij} = distance between vertex i of polygon₁ and vertex j of polygon₂.
 Polygons are scaled and centered.

Find the largest of the smallest vertex distances



Dissimilarity Based Classification of Polygons



Zero error difficult to reach!

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Non-Euclidean Representations: Causes

Computational Noise

Even for Euclidean distance matrices zero eigenvalues may show negative, e.g:

- $X = N(50,20)$: 50 points in 20 dimensions
- $D = \text{Dist}(X)$: 50 x 50 distance matrix
- Expected: $49-20 = 29$ zero eigenvalues
- Found: 15 negative eigenvalues

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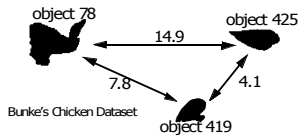
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Computational Problems

Large distances are overestimated due to computational problems



Weighted edit distance for strings

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Lack of information



1800:
Crossing the Jostedalbreen was impossible.
Travelling around (200 km) lasted 5 days.
Until the shared point X was found.
People could visit each other in 8 hours.

$D(V,J) = 5$ days
 $D(V,X) = 4$ hours
 $D(X,J) = 4$ hours

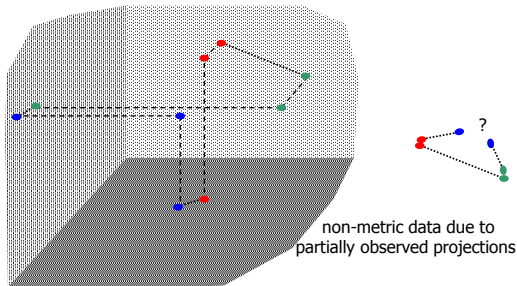
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Projections - Oclusions

Small distances are underestimated



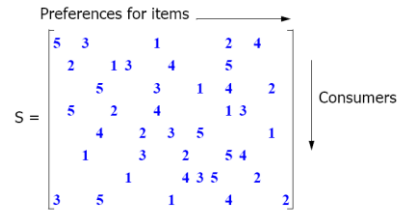
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Projections - Oclusions



Example: consumer preferences for recommendation systems

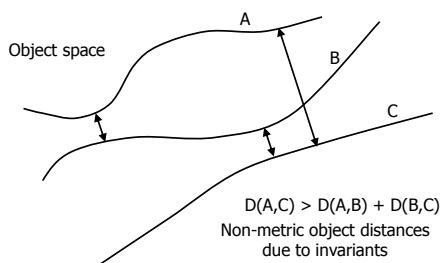
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Intrinsically Non-Euclidean Dissimilarity Measures Invariants



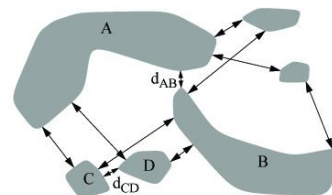
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Boundary distances



A set of boundary distances may characterize sets of datapoints:
Distances \rightarrow features

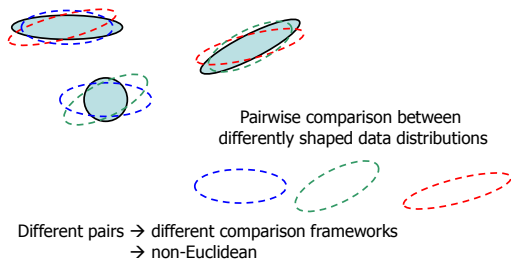
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Intrinsically Non-Euclidean Dissimilarity Measures Mahalanobis



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Objects may have an 'inner life'

In dissimilarity measures the 'inner life' of objects may be taken into account (e.g. invariants).

- Objects cannot be represented anymore as points
- Non-Euclidean dissimilarities

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Causes of Non-Euclidean Dissimilarities

- **Computational / Observational Limitations**
 - numerical accuracy problems
 - overestimated large distances (too difficult to compute)
 - underestimated small distances (one-sided view of objects)
- **Essential non-Euclidean distance definitions**
 - the human distance concept differs from the mathematical one
 - no global framework
 - invariants

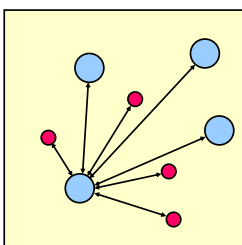
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Non-Euclidean Representations: Informativeness

Artificial Example ,Ball Distances



- Generate sets of balls (classes) uniformly, in a (hyper)cube; not intersecting.
- Balls of the same class have the same size.
- Compute all distances between the ball surfaces.
- > Dissimilarity matrix D

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Representation Strategies

Avoiding the PE space

Dissimilarity Space: $X = D$

Correcting

Associated space $X = \{[Xp, Xq], \emptyset\}$ $\tilde{d}_{ij}^2 = d_p^2(x_i, x_j) + d_q^2(x_i, x_j)$
 Positive space $X = X_p$ $\tilde{d}_{ij}^2 = d_p^2(x_i, x_j)$
 Negative space $X = X_q$ $\tilde{d}_{ij}^2 = d_q^2(x_i, x_j)$
 Additive Correction $\tilde{d}_{ij}^2 = d_{ij}^2 + c, i \neq j$ $X = \text{Embedding}(\tilde{D})$

As it is

Pseudo Euclidean Space $X = \{Xp, Xq\}$ $d_{ij}^2 = d_p^2(x_i, x_j) - d_q^2(x_i, x_j)$
 Classifiers to be developed further

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Balls3D

Classifier	PE Sp	Ass Sp	Pos Sp	Neg Sp	Cor Sp
1-NN	47.4 (2.0)	47.4 (2.0)	47.4 (2.0)	44.2 (1.5)	47.4 (2.0)
Parzen	45.7 (1.7)	45.5 (1.6)	45.6 (1.7)	35.5 (1.7)	45.7 (1.7)
NM	47.5 (2.0)	47.7 (2.0)	47.6 (1.9)	49.6 (0.2)	48.1 (1.8)
SVM-1	50.7 (2.2)	50.0 (2.7)	50.0 (2.5)	62.1 (1.7)	50.1 (2.0)

Classifier	PE Dis Sp	Ass Dis Sp	Pos Dis Sp	Neg Dis Sp	Cor Dis Sp
1-NN	49.8 (2.2)	49.8 (2.2)	49.8 (2.2)	5.1 (0.8)	49.7 (2.2)
Parzen	47.9 (2.2)	47.9 (2.2)	47.9 (2.2)	4.6 (0.5)	47.9 (2.2)
NM	49.8 (2.2)	49.8 (2.2)	49.8 (2.2)	5.0 (0.8)	49.9 (2.2)
SVM-1	50.2 (1.6)	50.8 (1.7)	50.7 (1.7)	1.9 (0.5)	49.8 (1.5)

10 x (2-fold crossvalidation of 50 objects per class)

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	size	classes	Non-Metric	NEF	Rand Err	Original, D	Positive, D_p	Negative, D_q
Chickenpieces45	446	5	0	0.156	0.791	0.022	0.132	0.175
Chickenpieces60	446	5	0	0.162	0.791	0.020	0.067	0.173
Chickenpieces90	446	5	0	0.152	0.791	0.022	0.052	0.148
Chickenpieces120	446	5	0	0.130	0.791	0.034	0.108	0.148
FlowCyto	612	3	1e-5	0.244	0.598	0.103	0.100	0.327
WoodyPlants50	791	14	5e-4	0.229	0.928	0.075	0.076	0.442
CatCortex	65	4	2e-3	0.208	0.738	0.046	0.077	0.662
Protein	213	4	0	0.001	0.718	0.01	0.000	0.000
Balls3D	200	2	3e-4	0.001	0.500	0.470	0.495	0.000
GaussM1	500	2	0	0.262	0.500	0.202	0.262	0.228
GaussM02	500	2	5e-4	0.393	0.500	0.204	0.174	0.252
CoilYork	288	4	8e-8	0.258	0.750	0.267	0.313	0.618
CoilDelftSame	288	4	0	0.027	0.750	0.413	0.417	0.597
CoilDelftDiff	288	4	8e-8	0.128	0.750	0.31	0.417	0.597
NewsGroups	600	4	4e-5	0.202	0.733	0.108	0.218	0.43560
BrainMRI	124	2	5e-5	0.112	0.499	0.226	0.218	0.556
Pedestrians	689	3	4e-8	0.111	0.348	0.010	0.015	0.030

Informative

Extremely Informative

Not Informative

Representation of non-Euclidean relations

- New objects may not fit into the space
- They should be included in the representation
- → Semi-supervised learning
- → Transductive learning
- → Use out-of-data examples
- → Generalized dissimilarities

Conclusions

- Pseudo Euclidean Space (PES) is sometimes informative (corrections are not helpful).
- The corresponding problems may be intrinsic non-Euclidean
- Classifiers for non-Euclidean data have to be studied further

Final Words

- Real world objects are not points
- Objects have a size
- Relations are non-Euclidean
- Non-Euclidean generalization procedures are needed

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